# NAG C Library Function Document

# nag zgelqf (f08avc)

# 1 Purpose

nag zgelqf (f08avc) computes the LQ factorization of a complex m by n matrix.

# 2 Specification

# 3 Description

nag\_zgelqf (f08avc) forms the LQ factorization of an arbitrary rectangular complex m by n matrix. No pivoting is performed.

If  $m \le n$ , the factorization is given by:

$$A = (L \quad 0)Q$$

where L is an m by m lower triangular matrix (with real diagonal elements) and Q is an n by n unitary matrix. It is sometimes more convenient to write the factorization as

$$A = (L \quad 0) \begin{pmatrix} Q_1 \\ Q_2 \end{pmatrix}$$

which reduces to

$$A = LQ_1$$
,

where  $Q_1$  consists of the first m rows of Q, and  $Q_2$  the remaining n-m rows.

If m > n, L is trapezoidal, and the factorization can be written

$$A = \begin{pmatrix} L_1 \\ L_2 \end{pmatrix} Q$$

where  $L_1$  is lower triangular and  $L_2$  is rectangular.

The LQ factorization of A is essentially the same as the QR factorization of  $A^H$ , since

$$A = \left( \begin{array}{cc} L & 0 \end{array} \right) Q \Leftrightarrow A^H = Q^H \bigg( \begin{array}{c} L^H \\ 0 \end{array} \bigg).$$

The matrix Q is not formed explicitly but is represented as a product of min(m, n) elementary reflectors (see the f08 Chapter Introduction for details). Functions are provided to work with Q in this representation (see Section 8).

Note also that for any k < m, the information returned in the first k rows of the array **a** represents an LQ factorization of the first k rows of the original matrix A.

## 4 References

None.

#### 5 Parameters

1: **order** – Nag\_OrderType

Input

On entry: the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by

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**order** = **Nag\_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.

Constraint: order = Nag\_RowMajor or Nag\_ColMajor.

2:  $\mathbf{m}$  – Integer Input

On entry: m, the number of rows of the matrix A.

Constraint:  $\mathbf{m} \geq 0$ .

3: **n** – Integer

On entry: n, the number of columns of the matrix A.

Constraint:  $\mathbf{n} \geq 0$ .

4:  $\mathbf{a}[dim]$  – Complex

Input/Output

**Note:** the dimension, dim, of the array **a** must be at least  $max(1, pda \times n)$  when **order** = Nag\_ColMajor and at least  $max(1, pda \times m)$  when **order** = Nag\_RowMajor.

If order = Nag\_ColMajor, the (i, j)th element of the matrix A is stored in  $\mathbf{a}[(j-1) \times \mathbf{pda} + i - 1]$  and if order = Nag\_RowMajor, the (i, j)th element of the matrix A is stored in  $\mathbf{a}[(i-1) \times \mathbf{pda} + j - 1]$ .

On entry: the m by n matrix A.

On exit: if  $m \le n$ , the elements above the diagonal are overwritten by details of the unitary matrix Q and the lower triangle is overwritten by the corresponding elements of the m by m lower triangular matrix L.

If m > n, the strictly upper triangular part is overwritten by details of the unitary matrix Q and the remaining elements are overwritten by the corresponding elements of the m by n lower trapezoidal matrix L.

The diagonal elements of L are real.

5: **pda** – Integer Input

On entry: the stride separating matrix row or column elements (depending on the value of **order**) in the array **a**.

Constraints:

```
if order = Nag_ColMajor, pda \geq \max(1, \mathbf{m}); if order = Nag_RowMajor, pda \geq \max(1, \mathbf{n}).
```

6: tau[dim] – Complex

Output

**Note:** the dimension, dim, of the array tau must be at least  $max(1, min(\mathbf{m}, \mathbf{n}))$ .

On exit: further details of the unitary matrix Q.

7: **fail** – NagError \*

Output

The NAG error parameter (see the Essential Introduction).

## 6 Error Indicators and Warnings

## NE INT

```
On entry, \mathbf{m} = \langle value \rangle.
Constraint: \mathbf{m} \geq 0.
On entry, \mathbf{n} = \langle value \rangle.
Constraint: \mathbf{n} > 0.
```

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```
On entry, \mathbf{pda} = \langle value \rangle. Constraint: \mathbf{pda} > 0.
```

#### NE INT 2

```
On entry, \mathbf{pda} = \langle value \rangle, \mathbf{m} = \langle value \rangle.
Constraint: \mathbf{pda} \ge \max(1, \mathbf{m}).
On entry, \mathbf{pda} = \langle value \rangle, \mathbf{n} = \langle value \rangle.
Constraint: \mathbf{pda} \ge \max(1, \mathbf{n}).
```

#### NE ALLOC FAIL

Memory allocation failed.

#### NE\_BAD\_PARAM

On entry, parameter (value) had an illegal value.

# **NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

# 7 Accuracy

The computed factorization is the exact factorization of a nearby matrix A + E, where

$$||E||_2 = O(\epsilon)||A||_2$$

and  $\epsilon$  is the *machine precision*.

## **8** Further Comments

The total number of real floating-point operations is approximately  $\frac{8}{3}m^2(3n-m)$  if  $m \le n$  or  $\frac{8}{7}n^2(3m-n)$  if m > n.

To form the unitary matrix Q this function may be followed by a call to nag zunglq (f08awc):

```
nag_zunglq (order,n,n,MIN(m,n),&a,pda,tau,&fail)
```

but note that the first dimension of the array **a**, specified by the parameter **pda**, must be at least **n**, which may be larger than was required by nag\_zgelqf (f08avc).

When  $m \le n$ , it is often only the first m rows of Q that are required, and they may be formed by the call:

```
nag_zunglq (order,m,n,m,&a,pda,tau,&fail)
```

To apply Q to an arbitrary complex rectangular matrix C, this function may be followed by a call to nag zunmlq (f08axc). For example,

```
nag_zunmlq (order,Nag_LeftSide,Nag_ConjTrans,m,p,MIN(m,n),&a,pda,
tau,&c,pdc,&fail)
```

forms the matrix product  $C = Q^{H}C$ , where C is m by p.

The real analogue of this function is nag dgelqf (f08ahc).

## 9 Example

To find the minimum-norm solutions of the under-determined systems of linear equations

$$Ax_1 = b_1$$
 and  $Ax_2 = b_2$ 

where  $b_1$  and  $b_2$  are the columns of the matrix B,

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$$A = \begin{pmatrix} 0.28 - 0.36i & 0.50 - 0.86i & -0.77 - 0.48i & 1.58 + 0.66i \\ -0.50 - 1.10i & -1.21 + 0.76i & -0.32 - 0.24i & -0.27 - 1.15i \\ 0.36 - 0.51i & -0.07 + 1.33i & -0.75 + 0.47i & -0.08 + 1.01i \end{pmatrix}$$

and

$$B = \begin{pmatrix} -1.35 + 0.19i & 4.83 - 2.67i \\ 9.41 - 3.56i & -7.28 + 3.34i \\ -7.57 + 6.93i & 0.62 + 4.53i \end{pmatrix}.$$

#### 9.1 Program Text

```
/* nag_zgelqf (f08avc) Example Program.
 * Copyright 2001 Numerical Algorithms Group.
* Mark 7, 2001.
*/
#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <naga02.h>
#include <nagf07.h>
#include <nagf08.h>
#include <nagx04.h>
int main(void)
  /* Scalars */
 Integer i, j, m, n, nrhs, pda, pdb, tau_len;
Integer exit_status=0;
  NagError fail;
  Nag_OrderType order;
  /* Arrays */
  Complex *a=0, *b=0, *tau=0;
#ifdef NAG_COLUMN_MAJOR
#define A(I,J) a[(J-1)*pda + I - 1] #define B(I,J) b[(J-1)*pdb + I - 1]
 order = Nag_ColMajor;
#else
#define A(I,J) a[(I-1)*pda + J - 1] #define B(I,J) b[(I-1)*pdb + J - 1]
 order = Nag_RowMajor;
#endif
  INIT_FAIL(fail);
  Vprintf("f08avc Example Program Results\n\n");
  /* Skip heading in data file */
  Vscanf("%*[^\n] ");
  Vscanf("%ld%ld%ld%*[^\n]", &m, &n, &nrhs);
#ifdef NAG_COLUMN_MAJOR
  pda = m;
  pdb = n;
#else
  pda = n;
 pdb = nrhs;
#endif
  tau_len = MIN(m,n);
  /* Allocate memory */
  if (!(a = NAG\_ALLOC(m * n, Complex))|
       !(b = NAG_ALLOC(n * nrhs, Complex)) ||
        !(tau = NAG_ALLOC(tau_len, Complex)) )
```

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```
Vprintf("Allocation failure\n");
     exit_status = -1;
     goto END;
 /* Read A and B from data file */
 for (i = 1; i \le m; ++i)
     for (j = 1; j \le n; ++j)
       Vscanf(" (%lf , %lf )", &A(i,j).re, &A(i,j).im);
 Vscanf("%*[^\n] ");
 for (i = 1; i \le m; ++i)
     for (j = 1; j \le nrhs; ++j)
       Vscanf(" ( %lf , %lf )", &B(i,j).re, &B(i,j).im);
 Vscanf("%*[^\n] ");
 /* Compute the LQ factorization of A */
 f08avc(order, m, n, a, pda, tau, &fail);
 if (fail.code != NE_NOERROR)
   {
    Vprintf("Error from f08avc.\n%s\n", fail.message);
     exit_status = 1;
     goto END;
  }
 /* Solve L*Y = B, storing the result in B */
 f07tsc(order, Nag_Lower, Nag_NoTrans, Nag_NonUnitDiag, m,
       nrhs, a, pda, b, pdb, &fail);
 if (fail.code != NE_NOERROR)
   {
    Vprintf("Error from f07tsc.\n%s\n", fail.message);
     exit_status = 1;
     goto END;
  }
 /* Set rows (M+1) to N of B to zero */
 if (m < n)
   {
     for (i = m + 1; i \le n; ++i)
         for (j = 1; j \le nrhs; ++j)
           {
            B(i,j).re = 0.0;
             B(i,j).im = 0.0;
           }
       }
 /* Compute minimum-norm solution X = (Q**H)*B in B */
 f08axc(order, Nag_LeftSide, Nag_ConjTrans, n, nrhs, m, a, pda,
 tau, b, pdb, &fail);
if (fail.code != NE_NOERROR)
    Vprintf("Error from f08axc.\n%s\n", fail.message);
     exit_status = 1;
     goto END;
 /* Print minimum-norm solution(s) */
 Nag_IntegerLabels, 0, Nag_IntegerLabels, 0, 80, 0, 0, &fail);
 if (fail.code != NE_NOERROR)
     Vprintf("Error from x04dbc.\n%s\n", fail.message);
     exit_status = 1;
     goto END;
END:
```

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```
if (a) NAG_FREE(a);
if (b) NAG_FREE(b);
if (tau) NAG_FREE(tau);
return exit_status;
```

#### 9.2 Program Data

### 9.3 Program Results

```
f08avc Example Program Results
```

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